Simple example of using BibT_EX

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Abstract

This document illustrates a small example of using $BibT_EX$. It is basically intended for a novice to download and see that $BibT_EX$ works on his machine. Note: Both this file (*simple_example.lyx*) and the file with $BibT_EX$ references (*references.bib*) are needed, so download both and put them in the same directory.

1 Instructions

In order to use BibT_EX, you need to have a database with references (a $BibT_EX$ -file, typically with the extension .*bib*). This example comes with such a file already, *references.bib*, that you should have put in the same directory as this file (*simple_example.lyx*). If you did the above, you should be able to view this example by using the menu: <u>View DVI</u>.

2 Creating this example

Here are the instructions that were followed in order to create the citations in this file:

1. To insert a **BibT_EX-inset**, i.e. the thing that will appear as your list of references in the end, first move the cursor to where you want the bibliography and then use the menu: Insert \triangleright Lists & TOC \triangleright BibT_EX Reference.

A dialog should immediately pop up with the title $BibT_EX$. Now you press the button **Browse** and select the file *references.bib*. Then press **Add** and the file should appear in the list of databases.

The *style* used in this document is *plainnat*, so choose that at the bottom of the dialog and finally press **OK** to close the dialog.

2. To insert an actual citation, i.e. the thing that often appear as [1], move the cursor to where you want it and then use the menu: Insert ▷ Citation Reference.

or simply press **M-i c**. This should pop up another dialog called *Citation* that contains a list of available references. In particular, you should see an entry with the *BibTeX citation key* Ridder-strom:2003:LLC. Double-click on that entry to add it to the list of selected references, and then close the dialog. This should insert a *citation-inset*, like this one: [Ridderström(2003)].

That was really it and if your system is properly configured, just run $\underline{V}iew \triangleright \underline{D}VI$ to see the result.

References

[Ridderström(2003)] Christian Ridderström. Legged locomotion: Balance, control and tools — from equation to action. PhD thesis, The Royal Inst. of Technology, SE-100 44 Stockholm, Sweden, May 2003. URL http://www.md.kth.se/~cas/publications.